## Supplement to Appendix B: The Firm's Innovation Policy

Denote the optimal innovation policy of the firm as I(n). It is convenient to express the optimal policy in terms of the optimal innovation intensity  $\lambda(n) = I(n)/n$ . The value of a firm with n products as of date 0 is thus

$$V(n) = E\left[\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(N_t))] N_t dt \mid N_0 = n\right]$$

The stochastic process  $\{N_t\}$  for the size of the firm then evolves on the integers, starting at  $N_0 = n$ , in the following manner. From some state m there is a Poisson hazard  $\lambda(m)m$ of transiting to state m + 1 and an independent Poisson hazard  $\mu m$  of transiting to state m - 1. The current flow return to the firm in state m is  $[\overline{\pi} - c(\lambda(m))]m$ .

Now consider stochastic processes  $\{N_t^k\}$  for k = 1, 2, ..., n. Suppose at date t that  $N_t^1 = m^1, N_t^2 = m^2, ..., N_t^n = m^n$ . If we think of process k as the size of the kth firm, then there is a Poisson hazard  $\lambda(m^k)m^k$  of this process transiting to state  $m^k + 1$  and an independent Poisson hazard  $\mu m^k$  of it transiting to state  $m^k - 1$ . The processes of n such firms will evolve independently of each other. The current flow return to the kth firm in state  $m^k$  will be  $[\overline{\pi} - c(\lambda(m^k))]m^k$ .

Alternatively, suppose we think of  $\sum_{k=1}^{n} N_t^k$  as the size of one firm at date t, and define

 $m = \sum_{k=1}^{n} m^{k}$ . Under the control of a single firm, this sum will evolve as described earlier, that is, from some state m there is a Poisson hazard  $\lambda(m)m$  of transiting to state m+1 and an independent Poisson hazard  $\mu m$  of transiting to state m-1. We can also imagine this one firm controlling each of the individual processes  $\{N_{t}^{k}\}$  separately. From state  $m^{k}$  there is a Poisson hazard  $\lambda(m)m^{k}$  for process k to transit to state  $m^{k}+1$  and a hazard  $\mu m^{k}$  of it transiting to state  $m^{k}-1$ . By the summability of Poisson hazards, it is clear that it makes no difference whether the firm controls the the n individual processes or just their sum. Similarly the flow return is the same since  $\sum_{k=1}^{n} [\overline{\pi} - c(\lambda(m))]m^{k} =$  $[\overline{\pi} - c(\lambda(m))] \sum_{k=1}^{n} m^{k} = [\overline{\pi} - c(\lambda(m))]m$ .

We want to use these results to derive properties of the optimal policy and the value function. First we show that a size n firm does at least as well as if it followed the policies

of *n* separate size 1 firms. Hence,  $V(n) \ge nV(1)$ :

$$\begin{split} V(n) &= E\left[\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(\sum_{k=1}^{n} N_{t}^{k}))]\left(\sum_{k=1}^{n} N_{t}^{k}\right) dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= E\left[\sum_{k=1}^{n} \left(\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(\sum_{k'=1}^{n} N_{t}^{k'}))]N_{t}^{k} dt\right) \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(\sum_{k'=1}^{n} N_{t}^{k'}))]N_{t}^{k} dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &\geq \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(N_{t}^{k}))]N_{t}^{k} dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(N_{t}^{k}))]N_{t}^{k} dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt}[\overline{\pi} - c(\lambda(N_{t}^{k}))]N_{t}^{k} dt \mid N_{0}^{k} = 1\right] \\ &= \sum_{k=1}^{n} V(1) \\ &= nV(1). \end{split}$$

Next we show that n size 1 firms do at least as well as if they joined together and followed the policy of one size n firm. Hence  $nV(1) \ge V(n)$ :

$$\begin{split} nV(1) &= \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(N_{t}^{k}))] N_{t}^{k} dt \mid N_{0}^{k} = 1\right] \\ &= \sum_{k=1}^{n} E\left[\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(N_{t}^{k}))] N_{t}^{k} dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= E\left[\sum_{k=1}^{n} \left(\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(N_{t}^{k}))] N_{t}^{k} dt\right) \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &\geq E\left[\sum_{k=1}^{n} \left(\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(\sum_{k=1}^{n} N_{t}^{k'}))] N_{t}^{k} dt\right) \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= E\left[\int_{0}^{\infty} e^{-rt} [\overline{\pi} - c(\lambda(\sum_{k=1}^{n} N_{t}^{k}))] \left(\sum_{k=1}^{n} N_{t}^{k}\right) dt \mid N_{0}^{1} = 1, N_{0}^{2} = 1, \dots, N_{0}^{n} = 1\right] \\ &= V(n) \end{split}$$

For both inequalities to hold it must be that V(n) = nV(1). It follows that  $\lambda(n)$  is a constant and so the optimal policy is  $I(n) = \lambda n$ .