## Selling Experiments

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## Introduction

Data buyer - a decision maker under uncertainty:

- has partial and private information
- can acquire additional information

Data seller offers additional information:

- how much information to provide and at what price?
- how to provide different information to different data buyers?

Interpretation: selling access to a database as in Acxiom, Bluekai, DoubleClick Ad Exchange

## Example: Behavioral Retargeting

- firms tailor online advertising levels to individual users
- targeting requires information about characteristics of individual users.
- different firms have different "first-party" information on users $\Rightarrow$ heterogeneous valuation for additional information
- data seller has information "third party" on individual characteristics
- data seller can offer to reveal certain attributes


## Information via Experiments

- data seller offers "information product":
- = experiment (in the statistical sense of Blackwell)
- provide statistical information about payoff-relevant state
- value of experiment depends on decision maker's private information - his beliefs
- decision maker's private beliefs are his type
- data seller has (common) prior over types


## Analysis

- optimal versioning of information product: design of information
- optimal selling of information product: price of information
- importantly: only information product itself is contractible
- by contrast, action of decision maker or realized state are not contractible


## Results

- a menu of experiments is offered
- menu contains only "simple" items, experiments
- menu is coarser than diversity of data buyers (types)
- linearity (in probabilities) limits the use of versioning
- systematic distortions in information provided
- screening facilitated by "directional information"


## Related Literature

## Selling Information

Admati and Pfleiderer (1986, 1990), Eső and Szentes (2007), Babaioff (2012), "Selling Cookies" AEJ Micro (2015).

## Information Impacts Prices

Johnson and Myatt (2006), Bergemann and Pesendorfer (2007), "Targeting in Advertising Markets" RAND (2011).

Persuasion
Rayo and Segal (2010), Kamenica and Gentzkow (2011),

## Model

- single decision-maker (buyer of information)
- finite actions

$$
a_{1}, \ldots, a_{I} \in A
$$

- finite states

$$
\omega_{1}, \ldots, \omega_{J} \in \Omega
$$

- ex-post utility

$$
u\left(a_{i}, \omega_{j}\right)
$$

- leading example, matching action to state $|I|=|J|$ :

$$
u\left(a_{i}, \omega_{j}\right)=\mathbf{1}_{[i=j]} .
$$

## Common Prior and Private Information

- common prior probability over states

$$
\mu \in \Delta \Omega
$$

- decision maker privately observes an initial signal $r \in R$ :

$$
\lambda: \Omega \rightarrow \Delta R
$$

- decision maker forms initial belief $\theta \in \Delta \Omega$ given signal $r$ :

$$
\theta_{r}(\omega)=\frac{\lambda(r \mid \omega) \mu(\omega)}{\sum_{\omega^{\prime}} \lambda\left(r \mid \omega^{\prime}\right) \mu\left(\omega^{\prime}\right)}
$$

- initial beliefs $\theta$ are private information of data buyer
- from data seller's point of view: $\lambda$ induces distribution of initial beliefs $F(\theta)$.


## Experiment

- data seller provides information as "experiment"
- an experiment (information structure) $I=\{S, \pi\}$ consists of signals $s \in S$ and likelihood function:

$$
\pi: \Omega \rightarrow \triangle S
$$

- type $r$ and signal $s$ independent - conditional on state $\omega$ :

$$
\operatorname{Pr}((r, s) \mid \omega)=\lambda(r \mid \omega) \cdot \pi(s \mid \omega), \quad \forall r, s, \omega
$$

- costless provision of information (data is already stored);


## Data Seller

- data seller can offer a menu of experiments

$$
\mathcal{M}=\{\mathcal{I}, t\}
$$

where each item on menu $\mathcal{I}$ is an experiment $I$ :

$$
\mathcal{I}=\{I\} \quad t: \mathcal{I} \rightarrow \mathbb{R}^{+}
$$

- each experiment $I$ has a price $t$
- note: action $a$ and state $\omega$ are not contractible
- thus: scoring rules and other belief elicitations schemes are not available
- price of information is determined before realization of $\omega$


## Timing of Information

(1) type $\theta$ of decision maker is realized
(2) seller offers menu of experiments $\mathcal{I}$
(3) decision maker $\theta$ chooses among experiments $\mathcal{I}$
(1) signal $s$ of experiment is realized, action $a$ is taken

## Interpretation: Big Data

- a continuum of consumers: $i \in[0,1]$,
- comsumer $i$ spends $\omega \in \mathbb{R}_{+}$per website (budget $\omega$ )
- distribution of budgets $\mu \in \Delta(\Omega)$ in population
- type $\theta$ of retailer is distribution of consumer budgets at its website
- distribution of consumers with budget $\omega$ over retailer $\theta: \lambda(\cdot \mid \omega)$
- think $\theta=$ Walmart, JC Penney, Sears, Macy


## Interpretation: Data Base and Demand for Data

- data seller (data base) has record of past digital purchases of $i$, thus knows of budget $\omega$ of $i$
- database can offer estimate, narrower or wider income brackets for every $i$ and $\omega$
- at random times consumer $i$ with budget $\omega$ has change of taste
i.e. new/renewal draw according to $\lambda(\cdot \mid \omega)$
- when $i$ appears for the first time at retailer $\theta$ website, retailer might wish to acquire more information about $\omega$ of $i$
- query or "machine" interpretation: for every $i$ generate an estimate of $\omega$
- $\pi(s \mid \omega, i)$ is independent of $i$ conditionally on $\omega$
- $\pi(s \mid \omega)$ is independent of $r$ conditionally on $\omega$


## Value of Experiment

- buyer's payoff under partial information

$$
u(\theta) \triangleq \max _{a \in A} \mathbb{E}_{\theta}[u(a, \omega)]
$$

- value of experiment (net value of augmented information)

$$
V(I, \theta) \triangleq \mathbb{E}_{I, \theta}\left[\max _{a \in A} \mathbb{E}_{s, \theta}[u(a, \omega)]\right]-u(\theta)
$$

## Initial and Incremental Information

- interim probability

$$
\theta_{i}=\operatorname{Pr}\left(\omega=\omega_{i}\right)
$$

- likelihood function under experiment $I$...:

$$
\pi_{i j}=\operatorname{Pr}\left(s_{j} \mid \omega_{i}\right)
$$

- ... and in matrix form $\pi$ :

$$
\begin{array}{cccc} 
& & s_{j} & \\
& \pi_{11} & \pi_{1 j} & \cdots \\
\omega_{i} & \pi_{i 1} & \pi_{i j} & \cdots
\end{array}
$$

## Specific Experiments

- locally noise free (at $s_{j}$ ):

|  |  | $s_{j}$ |  |
| :---: | :---: | :---: | :---: |
|  | $\pi_{11}$ | 0 | $\cdots$ |
|  |  | 0 |  |
| $\omega_{i}$ | $\pi_{i 1}$ | $\pi_{i j}$ | $\cdots$ |
|  |  | 0 |  |

- locally non-dispersed (at $\omega_{i}$ )

|  |  |  | $s_{j}$ |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\pi_{11}$ |  | $\pi_{1_{j}}$ | $\cdots$ |
| $\omega_{i}$ | 0 | 0 | 1 | 0 |

- perfectly informative

$$
\pi_{i j}= \begin{cases}1, & \text { if } i=j \\ 0, & \text { if } i \neq j\end{cases}
$$

is noise free and non-dispersed, globally

## Value of Experiment

- given matching action and state:

$$
u\left(a_{i}, \omega_{j}\right)= \begin{cases}1, & \text { if } i=j \\ 0, & \text { if } i \neq j\end{cases}
$$

- value of experiment $I$ for buyer $\theta$ :

$$
V(I, \theta)=\sum_{j} \max _{i}\left\{\theta_{i} \pi_{i j}\right\}-\max _{i}\left\{\theta_{i}\right\}
$$

- posterior belief: interim belief $\theta_{i}$ and signal $s_{j}$ :

$$
\theta_{i} \pi_{i j}
$$

- experiment provides a random allocation, $s_{1}, \ldots, s_{J}$ to an agent with unit demand $\max _{i}\left\{\theta_{i} \pi_{i j}\right\}$


## Geometry of Value of Experiment

- three states $\omega_{1}, \omega_{2}, \omega_{3}$
- perfect information experiment
- interim belief $\theta=\left(\theta_{1}, \theta_{2}, 1-\theta_{1}-\theta_{2}\right)$
- every edge represents a change in decision given interim belief



## Seller's Problem

- seller offers a menu of experiments

$$
\mathcal{M}=\{\mathcal{I}, t\}
$$

with

$$
\mathcal{I}=\{I\} \quad t: \mathcal{I} \rightarrow \mathbb{R}^{+}
$$

- direct mechanism

$$
\mathcal{M}=\{I(\theta), t(\theta)\} .
$$

- seller's objective function is subject to incentive and participation constraints:

$$
\begin{array}{ll} 
& \max _{\{I(\theta), t(\theta)\}} \int t(\theta) \mathrm{d} F(\theta), \\
\text { s.t. } & V(I(\theta), \theta)-t(\theta) \geq V\left(I\left(\theta^{\prime}\right), \theta\right)-t\left(\theta^{\prime}\right) \quad \forall \theta, \theta^{\prime}, \\
& V(I(\theta), \theta)-t(\theta) \geq 0 \quad \forall \theta .
\end{array}
$$

## First Steps

- possible continuum of experiments $I(\theta)$
- each experiment has a potentially complicated map:

$$
\text { states } \rightarrow \text { signals } \rightarrow \text { actions }
$$

- merge signals in $I(\theta)$ leading to the same action for type $\theta$


## Proposition (Maximal Cardinality of Signals)

In an optimal menu, the cardinality of the signal space of every experiment has at most the cardinality of the action space.

- $V(I(\theta), \theta)$ stays constant but $V\left(I(\theta), \theta^{\prime}\right)$ decreases $\forall \theta^{\prime} \neq \theta$ as value of misreport is reduced


## An Illustration: Binary States

- binary state, binary action:

$$
\begin{array}{c|cc}
u(a, \omega) & a=a_{H} & a=a_{L} \\
\hline \omega=\omega_{H} & \mathbf{1} & \mathbf{0} \\
\omega=\omega_{L} & \mathbf{0} & \mathbf{1}
\end{array}
$$

- let $\theta=\operatorname{Pr}\left(\omega=\omega_{H}\right)$
- by Proposition 1 restrict attention to experiments:

$$
I=\begin{array}{c|cc} 
& s_{H} & s_{L} \\
\hline \omega_{H} & \alpha & 1-\alpha \\
\omega_{L} & 1-\beta & \beta
\end{array}
$$

- wlog convention that $\alpha+\beta \geq 1$ (equivalent to monotone likelihood ratio)


## Value of Experiment with Binary Model

- value of experiment $(\alpha, \beta)$

$$
V(\alpha, \beta, \theta)=[\alpha \theta+\beta(1-\theta)-\max \{\theta, 1-\theta\}]^{+} .
$$

- locally non-dispersed at $\omega=\omega_{L}$, locally noise free at $s_{H}$ :

$$
I=\begin{array}{c|cc} 
& s_{H} & s_{L} \\
\hline \omega_{H} & \alpha & 1-\alpha \\
\omega_{L} & 0 & 1
\end{array}
$$

- directionally informative: information valuable for some types, but not for others
- valuable for DM who deems $\omega_{L}$ very likely
- not valuable for DM who deems $\omega_{H}$ very likely
- directionally informative for null hypothesis of $\omega_{L}$ :
- minimize false positive (type 1 error) to zero for $\omega_{L}$,
- maximize false negative (type 2 error) for $\omega_{H}$


## Value of a Perfectly Informative Experiment

- value of experiment $(\alpha, \beta)=(1,1)$ for type $\theta$.

- highest type is in the interior rather than on the boundary
- more than local incentive constraints, more than local participation constraints


## Value of a Directionally Informative Experiment



- distance $|\theta-1 / 2|$ not sufficient for value of experiment
- different slopes - differential gains of avoiding type 1 errors
- information has horizontal and vertical dimension of differentiation, information is always high-dimensional
- high degree of incompleteness in ranking of information structures


## Preferences over Experiments

Value of experiment $(\alpha, \beta)$ for type $\theta$

$$
V(\alpha, \beta, \theta)=(\alpha-\beta) \theta+\beta-\max \{\theta, 1-\theta\} .
$$

- $\beta=$ baseline informativeness (from payoff normalization).
- $\alpha-\beta=$ relative informativeness.
- two "goods" that cannot be produced independently.


## Feasible Set of Experiments



## Indifference Curves for Given Type

- value of experiment is

$$
V(\alpha, \beta, \theta)=(\alpha-\beta) \theta+\beta-\max \{\theta, 1-\theta\}
$$



- higher $\theta$ have stronger preference for differential $\alpha-\beta$


## Value of Baseline Information

- incremental change in the baseline information $\beta$
- while keeping the relative informativeness $\alpha-\beta$ constant

$$
V(\alpha+\delta, \beta+\delta, \theta)-V(\alpha, \beta, \theta)=\delta, \quad \forall \theta
$$

- uniform increase in value of experiment for all types



## Set of Optimal Experiments

- maximal baseline informativeness for any given relative

informativeness
- reduce choice of experiment to one-dimensional problem:

$$
q \triangleq \alpha-\beta
$$

## Structure of Optimal Menu

- for finitely many states and actions, possibly continuum of types


## Proposition (Optimal Menu and Non-Dispersed Information)

(1) The fully informative experiment, $\pi_{i i}=1$ for all $i$, is always part of the optimal menu.
(2) Every experiment in an optimal menu is locally non-dispersed, i.e., $\pi_{i i}=1$ for some $i$.

| states/types | binary | continuum |
| :---: | :---: | :---: |
| binary | $\cdots$ | $\ldots$ |
| finite | $\cdots$ | $\checkmark$ |

## Binary Types and Binary States: First Example

- binary types: $\theta \in\{2 / 10,7 / 10\}$ with equal probability
- type $\theta=7 / 10$ is less informed
- a possible solution (with slack incentive constraints)



## Binary Types: An Optimal Solution



- two experiments
- no distortion at the top ( $\theta$ closer to $1 / 2$ );
- no rent at the bottom;
- corner solution - no rent at the top


## Binary Types and Binary States

- two types are congruent if they choose the same action given their interim belief, otherwise non-congruent
- high type is less informed than low type:

$$
\left|\theta^{H}-1 / 2\right| \leq\left|\theta^{L}-1 / 2\right|, \quad \theta^{H} \geq 1 / 2
$$

- recall prior probability of high type

$$
\gamma=\operatorname{Pr}\left(\theta=\theta^{H}\right)
$$

- critical frequency of high vs low types:

$$
\bar{\gamma} \triangleq \frac{1-\theta^{L}}{1-\theta^{H}}
$$

## Optimal Experiment

## Proposition

(1) With congruent priors, the seller offers the perfectly informative experiment only; both types participate if and only if $\gamma \leq \bar{\gamma}=\left(1-\theta^{L}\right) /\left(1-\theta^{H}\right)$.
(2) With non-congruent priors and $\gamma \leq \bar{\gamma}$, both types buy the fully informative experiment.
(3) With non-congruent priors and $\gamma>\bar{\gamma}$, the high type buys the fully informative experiment and the low type buys a partially informative experiment:

$$
\alpha=\frac{2 \theta^{H}-1}{\theta^{H}-\theta^{L}} \quad \text { and } \quad \beta=1 ;
$$

and the seller extracts the entire surplus.

- quality of information and comparative statics of $1-\alpha$ in $\gamma, \theta^{L}, \theta^{H}$


## Many States and Many Actions

- we maintain binary states

$$
\theta \in\left\{\theta_{L}, \theta_{H}\right\}
$$

and allow for many states (and many actions)

- order the states $\omega$ by their likelihood ratios:

$$
\frac{\theta_{1}^{L}}{\theta_{1}^{H}} \leq \cdots \leq \frac{\theta_{i}^{L}}{\theta_{i}^{H}} \leq \cdots \leq \frac{\theta_{N}^{L}}{\theta_{N}^{H}}
$$

- states $\omega_{i}$ with low indices are deemed more likely by $\theta^{H}$


## Optimal Experiment

- use disagreement across states to drive screening across types


## Proposition

There exists $i^{*}$ such that the optimal experiment $I\left(\theta^{L}\right)$ has $\pi_{i i}=0$ for all $i<i^{*}$ and $\pi_{i i}=1$ for all $i>i^{*}$.

- optimal experiment has lower-triangular shape

| 0 | $\cdots$ | 0 | $\pi_{1 i}$ | $\cdots$ | $\cdots$ | $\pi_{1 n}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\vdots$ |  | $\vdots$ | $\vdots$ |  |  | $\vdots$ |
| $\vdots$ |  | $\vdots$ | $\pi_{i i}$ | $\cdots$ | $\cdots$ | $\pi_{i n}$ |
| $\vdots$ |  | $\vdots$ | 0 | 1 | $\cdots$ | 0 |
| $\vdots$ |  | $\vdots$ | $\vdots$ | $\vdots$ | $\ddots$ | $\vdots$ |
| 0 | $\cdots$ | 0 | 0 | 0 | $\cdots$ | 1 |

- distribution of $\pi_{i}$. is not uniquely determined


## Continuum of Types

- return to binary states, allow continuum of types $\theta \in[0,1]$
- recall the value of experiment $q \in[-1,1]$ for type $\theta \in[0,1]$ :

$$
V(q, \theta)=[\theta q-\max \{q, 0\}+\min \{\theta, 1-\theta\}]^{+} .
$$

- single-crossing suggests $q$ increasing in $\theta$.
- types $\theta=0$ and $\theta=1$ receive zero rents.
- consider type $\theta=1 / 2$, derive additional condition.


## Incentive Compatibility

- rent of type $\theta=1 / 2$

$$
U(1 / 2)=U(0)+\int_{0}^{1 / 2} V_{\theta}(q, \theta) \mathrm{d} \theta=U(1)-\int_{1 / 2}^{1} V_{\theta}(q, \theta) \mathrm{d} \theta
$$

- define an allocation $q(\cdot)$ to be responsive if, for any $\theta$

$$
\begin{gathered}
\theta q(\theta)-\max \{q(\theta), 0\}+\min \{\theta, 1-\theta\} \leq 0 \\
\Rightarrow q(\theta)=\left\{\begin{array}{lll}
-1 & \text { if } & \theta<1 / 2 \\
+1 & \text { if } & \theta \geq 1 / 2
\end{array}\right.
\end{gathered}
$$

- if net utility of experiment is negative for $\theta$, then assign zero information experiment


## Incentive Compatibility

- rent of type $\theta=1 / 2$

$$
U(1 / 2)=\int_{0}^{1 / 2}(q(\theta)+1) \mathrm{d} \theta=-\int_{1 / 2}^{1}(q(\theta)-1) \mathrm{d} \theta
$$

## Proposition (Necessary Conditions)

If the allocation $q(\theta)$ is implementable and responsive then

$$
q(\theta) \in[-1,1] \text { is non-decreasing, }
$$

and

$$
\int_{0}^{1} q(\theta) d \theta=0
$$

- note: a different kind of constraint, a global constraint


## Seller's Problem

$$
\begin{gathered}
\max _{q(\theta)} \int_{0}^{1}\left[\left(\theta-\frac{1-F(\theta)}{f(\theta)}\right) q(\theta)-\max \{q(\theta), 0\}\right] f(\theta) \mathrm{d} \theta \\
\text { s.t. } q(\theta) \in[-1,1] \text { non-decreasing, } \\
\int_{0}^{1} q(\theta) \mathrm{d} \theta=0
\end{gathered}
$$

Piecewise linear (concave) problem with integral constraint.
Absent the integral constraint, corner solutions:

- $q^{*} \in\{-1,0,1\}$, i.e., all-or-nothing information, flat price.
- E.g., truncated support or symmetric distribution.


## Optimal Menu

## Proposition (Optimal Menu)

An optimal menu consists of at most two experiments.
(1) The first experiment is fully informative.
(2) The second experiment is locally non-dispersed and locally noisefree.

- coarse menu
- a continuum of types - yet only a binary choice is provided


## Properties of the Optimal Menu

Optimal mechanism involves $\leq 2$ bunching intervals.
Ideally, would sell $q=0$ at two different prices (for $\theta \lessgtr 1 / 2$ ).

- Symmetric distribution or truncated support $\rightarrow$ flat pricing.
- Second-best menu may contain $q=0$ only...
- ... or distort the "least profitable side."
- No further versioning is optimal.

Least informed types $\neq$ most valuable to the seller.
Type $\theta=1 / 2$ need not get efficient $q=0$.

## Conclusions: Selling Information

- selling incremental information to privately informed buyers.
- costless acquisition \& transmission, free degrading
- "uninterested seller" - packaging problem
- bayesian problem for buyers
- linear in probabilities: limited use of versioning
- screening across agents through directional information


## Seller's Problem

$$
\begin{gathered}
\max _{q(\theta)} \int_{0}^{1}\left[\left(\theta-\frac{1-F(\theta)}{f(\theta)}\right) q(\theta)-\max \{q(\theta), 0\}\right] f(\theta) \mathrm{d} \theta \\
\text { s.t. } q(\theta) \in[-1,1] \text { non-decreasing, } \\
\int_{0}^{1} q(\theta) \mathrm{d} \theta=0
\end{gathered}
$$

## Seller's Problem

$$
\begin{gathered}
\max _{q(\theta)} \int_{0}^{1}[(\theta f(\theta)+F(\theta)) q(\theta)-\max \{q(\theta), 0\} f(\theta)] \mathrm{d} \theta \\
\text { s.t. } q(\theta) \in[-1,1] \text { non-decreasing, } \\
\int_{0}^{1} q(\theta) \mathrm{d} \theta=0
\end{gathered}
$$

Consider "virtual values" for each experiment $q$ separately:

$$
\phi(\theta, q) \triangleq\left\{\begin{array}{ll}
\theta f(\theta)+F(\theta) & \text { for } \quad q<0 \\
(\theta-1) f(\theta)+F(\theta) & \text { for }
\end{array} \quad q>0\right.
$$

- $\phi=$ marginal value of going from $q(\theta)=-1$ to 0 to 1 .
- Problem is not separable: virtual value $\phi$ depends on $q$.


## General Case

- Let $\lambda$ denote the multiplier on the integral constraint (shadow cost of providing higher "quantity").
- Let $\bar{\phi}(\theta, q)$ denote the ironed virtual value for experiment $q$.


## Proposition (Optimal Allocation Rule)

Allocation $q^{*}(\theta)$ is optimal if and only if there exists $\lambda^{*} \geq 0$ s.t.

$$
q^{*}(\theta) \in \underset{q \in[-1,1]}{\arg \max }\left[\int_{0}^{q}\left(\bar{\phi}(\theta, x)-\lambda^{*}\right) d x\right] \text { for all } \theta
$$

has the "pooling property," and satisfies the integral constraint.

- Myerson (1981), Toikka (2011), Luenberger (1969).


## Example 1: Uniform Distribution



Virtual Values: $\phi(\theta,-1)$ in blue; $\phi(\theta, 1)$ in red.

## Example 1: Uniform Distribution



Virtual Values: $\phi(\theta,-1)$ in blue; $\phi(\theta, 1)$ in red.

## Example 1: Uniform Distribution



## Optimality of Flat Pricing

## Proposition (Flat Pricing)

The optimal menu contains only the fully informative experiment when any of the following conditions hold:
(1) the density $f(\theta)=0$ for all $\theta>1 / 2$ or $\theta<1 / 2$;
(2) the density $f(\theta)$ is symmetric around $\theta=1 / 2$.
(3) $F(\theta)+\theta f(\theta)$ and $F(\theta)+(\theta-1) f(\theta)$ are strictly increasing.

A second experiment is offered only if ironing is required.

## Non-monotone Density



Probability Density Function: informed types are frequent

## Example 2: Combination of Beta Distributions



## Example 2: Beta Distributions



## Example 2: Beta Distributions



## Example 2: Beta Distributions



## Example 2: Beta Distributions


need not get efficient $q=0$.

## Implications for Observables

- how to damage an information good
- should not observe arbitrarily damaged goods
- directional information: only type- $I$ or $I I$ errors
- should not observe multiple distortions of the same kind
- directional distortions $\sim$ disclosure of specific attributes (correlated with high- or low- value consumers).

